

A 2 kg mass is attached to a spring with spring constant of 272 N/m. The surrounding medium offers a resistance numerically equal to 24 times the velocity. The initially 4 m below the equilibrium position and given a downward velocity of 36 m/s. The motion is driven by an external driving force of $F(t) = 1200 \sin 8t$. Obtain the equation of motion.

Given:

$$\begin{aligned} m &= 2 \text{ kg}, & k &= 272 \text{ N/m}, & \beta &= 24, \\ x(0) &= +4 \text{ m}, & x'(0) &= +36 \text{ m/s}. \end{aligned}$$

The ODE (governing equation) is then

$$\begin{aligned} m x'' + \beta x' + k x = F(t) &\implies 2 x'' + 24 x' + 272 x = 1200 \sin 8t, \\ &\implies x'' + 12 x' + 136 x = 600 \sin 8t. \end{aligned} \tag{1}$$

STEP 1: COMPLEMENTARY SOLUTION

The characteristic equation

$$m^2 + 12m + 136 = 0$$

has roots

$$m_{1,2} = -6 \pm 10i.$$

Since the roots are complex, the complementary solution of Eq. (1) is *underdamped*:

$$x_c(t) = e^{-6t}(c_1 \cos 10t + c_2 \sin 10t). \tag{2}$$

STEP 2: PARTICULAR SOLUTION

Now we seek a particular solution of (1). We'll use **undetermined coefficients**:

Input Function:	Terms
$f = 600 \sin 8t$	$\sin 8t$
$f' = 4800 \cos 8t$	$\cos 8t$
$f'' = 38400 \sin 8t$	$\sin 8t$
List: $\cos 8t, \sin 8t$	

Q: Do any terms in the List already appear in x_c ?

A: No, so we need not modify the List.

So we seek a particular solution of (1) that is a linear combination of terms in the List:

$$x_p = a \cos 8t + b \sin 8t. \tag{3}$$

We substitute x_p into (1) and collect like terms to obtain

$$(72a + 96b) \cos 8t + (-96a + 72b) \sin 8t \equiv 600 \sin 8t.$$

Equate like terms:

$$\begin{aligned}\cos 8t &: 72a + 96b \equiv 0 \\ \sin 8t &: -96a + 72b \equiv 600\end{aligned}$$

We solve these to obtain $a = -4$ and $b = 3$.

So by (3), a particular solution of (1) is

$$x_p(t) = -4 \cos 8t + 3 \sin 8t. \quad (4)$$

STEP 3: GENERAL SOLUTION

Then the general solution of the nonhomogeneous problem (1) is

$$\begin{aligned}x(t) &= x_c + x_p \\ &= e^{-6t}(c_1 \cos 10t + c_2 \sin 10t) - 4 \cos 8t + 3 \sin 8t,\end{aligned} \quad (5)$$

and

$$\begin{aligned}x'(t) &= -6e^{-6t}(c_1 \cos 10t + c_2 \sin 10t) + e^{-6t}(-10c_1 \sin 10t + 10c_2 \cos 10t) \\ &\quad + 32 \sin 8t + 24 \cos 8t.\end{aligned} \quad (6)$$

STEP 4: APPLY INITIAL CONDITIONS:

The initial conditions were

$$x(0) = 4 \quad \text{and} \quad x'(0) = 36,$$

so from equations (5) and (6) we obtain

$$x(0) = c_1 - 4 \equiv 4, \quad (7)$$

$$x'(0) = -6c_1 + 10c_2 + 24 \equiv 36. \quad (8)$$

We solve equations (7) and (8) for c_1 and c_2 to obtain $c_1 = 8$ and $c_2 = 6$. So the solution (the *equation of motion*) is

$$x(t) = e^{-6t}(8 \cos 10t + 6 \sin 10t) - 4 \cos 8t + 3 \sin 8t. \quad (9)$$

NOTES & NEW CONCEPTS:

1. In this example, the complementary solution $x_c(t)$ (see Eq. (2)) represents *decaying oscillation*, i.e.,

$$x_c(t) \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

2. In this example, the particular solution $x_p(t)$ (see Eq. (4)) represents *simple harmonic motion*, i.e., constant amplitude oscillation. It does not decay to zero as $t \rightarrow \infty$ but oscillates with constant amplitude for all time.

3. When these events occur, we call

- $x_c(t)$ a *transient term* since it decays to zero, and
- $x_p(t)$ a *steady state term*.

In other words, in this example if time t is sufficiently large, then we may approximate the equation of motion $x(t)$, given by Eq. (9), by the particular solution x_p :

$$x(t) \approx x_p(t) = -4 \cos 8t + 3 \sin 8t.$$

Thus, if we're interested only in the steady state solution (the long term behavior of the system), then we merely need to perform Steps 1 and 2 and *not do Steps 3 and 4 at all* — *BIG time saver!*

Thus:

- The *steady state amplitude* (of oscillation) is

$$A_{ss} = A_p = \sqrt{(-4)^2 + (3)^2} = \sqrt{25} \text{ m} = 5 \text{ m}.$$

- The *steady state period* (of oscillation) is

$$T_{ss} \equiv \frac{2\pi}{8} = \frac{\pi}{4} \text{ sec/cycle},$$

which is the same as the period of the driving force $F(t)$.

- The *steady state frequency* (of oscillation) is

$$f_{ss} \equiv \frac{1}{T} = \frac{4}{\pi} \text{ cycles/sec} = \frac{4}{\pi} \text{ Hz},$$

which is the same as the frequency of the driving force $F(t)$.