The method of **Undetermined Coefficients** is used to construct a **particular solution** of a linear, **non**homogeneous ODE with constant coefficients:

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_2 y'' + a_1 y' + a_0 y = g(x)$$
(N)

when g(x) is any linear combination of functions of the form

 $k, x^m, e^{\alpha x}, x^m e^{\alpha x}, e^{\alpha x} \cos \beta x, e^{\alpha x} \sin \beta x, x^m e^{\alpha x} \cos \beta x, x^m e^{\alpha x} \sin \beta x.$

The function g(x) is often called the *input function*, the *forcing function*, or the *driving force*.

STEP 1:

Obtain the general solution of the associated homogeneous problem

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_2 y'' + a_1 y' + a_0 y = 0.$$
(H)

We did this in Section 4.3 to obtain

$$y_c = c_1 y_1 + c_2 y_2 + \dots + c_n y_n.$$
 (C)

This general solution of (H) is called the *complementary solution* of (N), so we now denote it by y_c .

Notes:

- 1. y_c is the general solution of (H), not of (N).
- 2. The functions y_1, \ldots, y_n are linearly independent solutions of (H), not of (N).

STEP 2:

Use **Undetermined Coefficients** to construct a *particular solution* y_p of the nonhomogeneous problem (N). This is the method we'll learn in Section 4.4.

STEP 3:

Then the general solution of the nonhomogeneous problem (N) is

$$y = y_c + y_p \,. \tag{G}$$

It is an n parameter family of solutions of (N).

STEP 4:

If there are any initial conditions, apply them to the general solution (G), NOT to solution (C)!