Chapter 4 Optimized Implementation of Logic Functions

- Logic Minimization
- Karnaugh Maps
- Systematic Approach for Logic Minimization
- Minimization of Incompletely Specified Functions
- Tabular Method for Minimization
- Practical Considerations

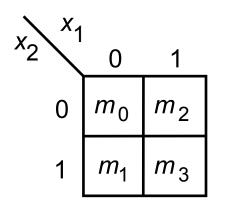
Logic Minimization

- **Goal**: find the *optimum* implementation of logic function.
- The *cost criteria* for determining the optimum (*lowest cost*) implementation may be defined by the designer, for example:
 - Hardware cost, measured as total number & size of logic gates
 - Propagation delay (from inputs to outputs)
 - Worst case
 - Average
 - Design time (effort)
 - For example quick product prototypes may be required in initial phases of a project with optimizations applied later
- Equally optimal but different solutions are possible
- We consider two-level realizations of logic functions (eg. SOP or POS)
- Different logic minimization techniques:
 - Algebraic Manipulation
 - Karnaugh Maps (typically for functions of max 5 or 6 variables)
 - Tabular Method
 - Heuristic Techniques, eg. Espresso

| <i>x</i> ₁ | <i>x</i> ₂ | f |
|-----------------------|-----------------------|----------------|
| 0 | 0 | m_0 |
| 0 | 1 | m ₁ |
| 1 | 0 | т ₂ |
| 1 | 1 | m ₃ |

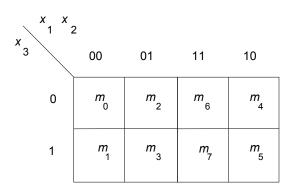
| <i>x</i> 1 | × 2 | x ₃ | f |
|------------|-----|----------------|-----------------------|
| 0 | 0 | 0 | m ₀ |
| 0 | 0 | 1 | m ₁ |
| 0 | 1 | 0 | m2 |
| 0 | 1 | 1 | m ₃ |
| 1 | 0 | 0 | <i>m</i> ₄ |
| 1 | 0 | 1 | m ₅ |
| 1 | 1 | 0 | m ₆ |
| 1 | 1 | 1 | m ₇ |
| | | | I |

(a) Truth table of 3-variable function



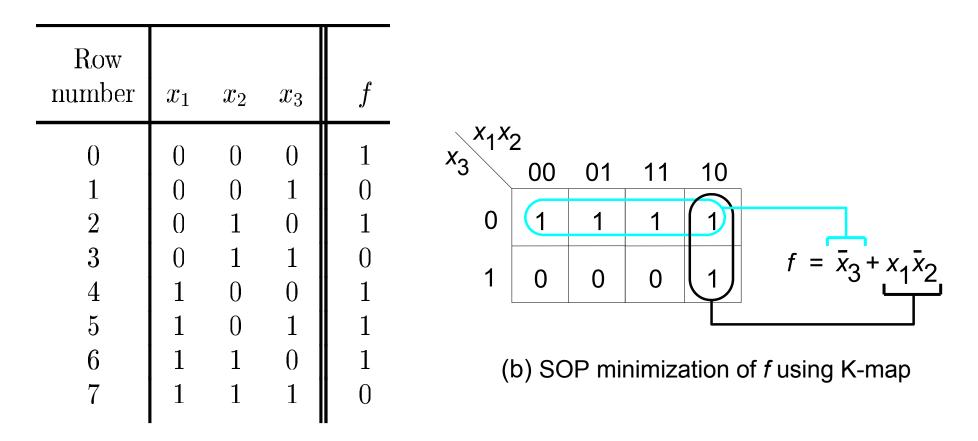
(b) Karnaugh map

(a) Truth table of 4-variable function



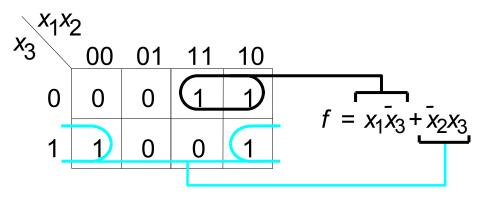
(b) Karnaugh map

Chapter 4-3



(a) The function $f(x_1, x_2, x_3) = \sum m(0, 2, 4, 5, 6)$.

| Row number | x_1 | x_2 | x_3 | $f(x_1, x_2, x_3)$ |
|---------------|-------|-------|-------|--------------------|
| 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 1 | 1 |
| 2 | 0 | 1 | 0 | 0 |
| 3 | 0 | 1 | 1 | 0 |
| 4 | 1 | 0 | 0 | 1 |
| 5 | 1 | 0 | 1 | 1 |
| 6 | 1 | 1 | 0 | 1 |
| 7 | 1 | 1 | 1 | 0 |



(b) SOP minimization of f using K-map

(a) The function $f(x_1, x_2, x_3) = \sum m(1, 4, 5, 6)$.

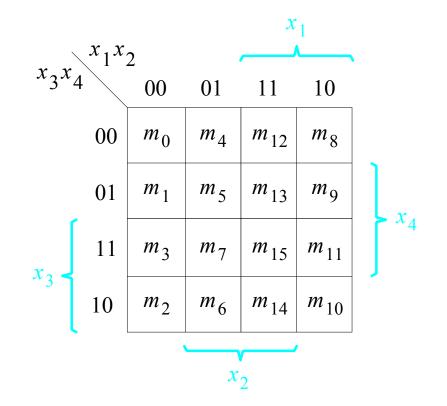
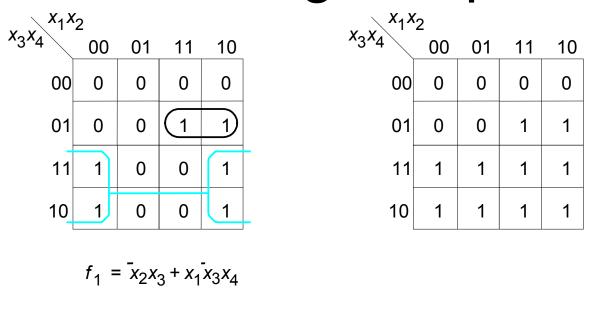


Figure 4.6. A four-variable Karnaugh map.



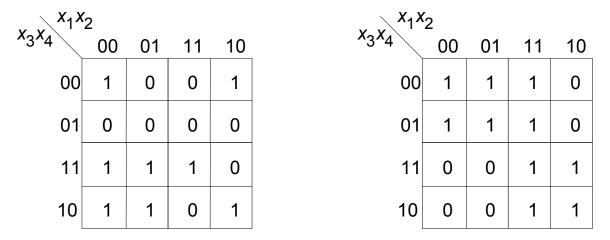


Figure 4.7. Examples of four-variable Karnaugh maps. Chapter 4-7

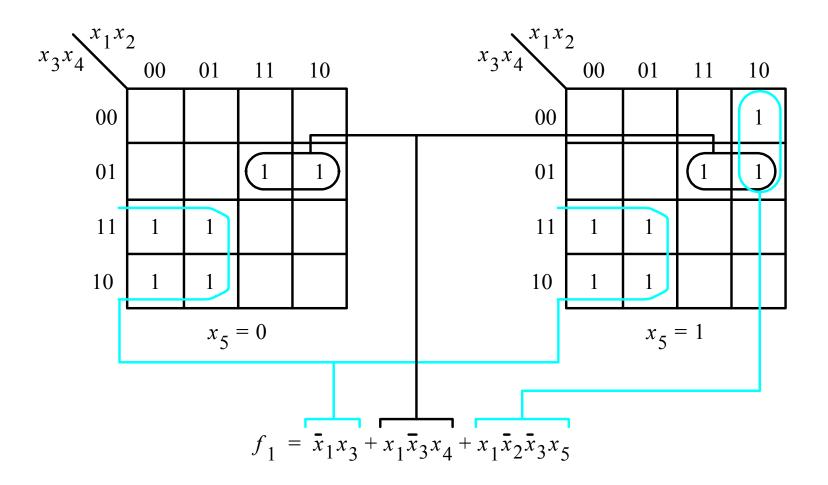


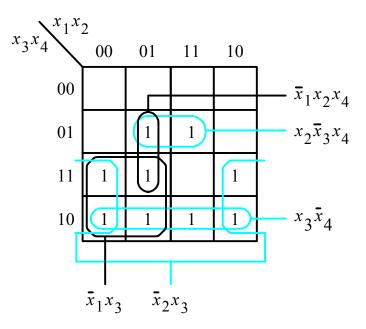
Figure 4.8. A five-variable Karnaugh map.

- Intuitive strategy: find as few and as large as possible groups of 1s that cover all cases where the function has a value of 1.
- Each group of 1s represented by a single product term.
- The larger the group of 1s, the fewer the number of variables in the corresponding product term.
- To describe the systematic approach for logic minimization, precisely define terminologies:
- *Literal* Each appearance of a variable in either normal or complemented form.
- Implicant a product term p is said to be implicant of f iff for all input combination for which p evaluates to 1 f also evaluates to 1.
- The most basic implicants of *f* are its minterms.
- *Prime Implicant* an implicant that can not be reduced (by combination) to another one with fewer literals.
- It is not possible to delete any literal in a prime implicant and still have a valid implicant.

- *Cover* A collection of implicants that account for all valuations for which a given function is equal to 1 is called a cover of that function.
- Cover defines a particular implementation of the function. A number of different covers exist for a logic function. Example:
 - A set of all minters for which f = 1 is a cover.
 - A set of all prime implicants is a cover.
- *Cost* the logic minimization criteria.
- For our purpose, we define the cost of a logic circuit as the number of gates plus the total number of inputs to all gates in the circuit.
- In general, the larger a circuit, the more important the cost issue becomes.
- Assumption: the primary input variables are available in both normal and complemented forms at zero cost. This is true, for example, in many PLDs.

- The lowest-cost implementation is achieved when the cover of a given function consists of prime implicants.
- How to determine the minimum-cost subset of prime implicants that will cover the function?
- If a prime implicant includes a minterm that is not included in any other prime implicant, such minterm is called *distinguished 1-cell*.
- A prime implicant containing one or more distinguished 1-cells is called *essential prime implicant*, and it must be included in the cover
- Steps of finding minimum-cost circuit:
 - 1. Generate all prime implicants for the given function *f*
 - 2. Find the set of essential prime implicants
 - 3. If the set of essential prime implicants covers all valuations for which f = 1, then this set is the desired cover of f. Otherwise, determine the non-essential prime implicants that should be added to form a complete minimum-cost cover.

 Example: Find the prime implicants, distinguished 1-cells, essential prime implicants and the minimum SOP representation for each of the following functions



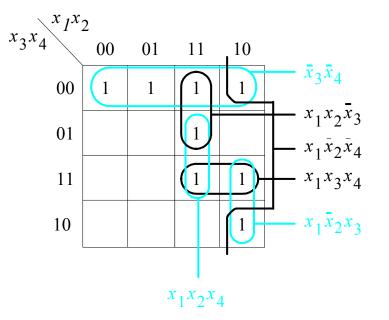


Figure 4.10. Four-variable function $f(x_1,...,x_4) = \sum m(2, 3, 5, 6, 7, 10, 11, 13, 14).$

Figure 4.11. The function $f(x_1,...,x_4) = \Sigma m(0, 4, 8, 10, 11, 12, 13, 15).$

• Sometimes there may not be any essential prime implicants at all. Alternative solutions of equal weight possible.

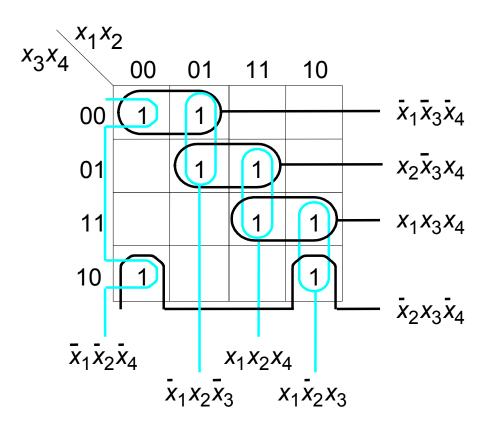


Figure 4.12. The function $f(x_1,...,x_4) = \sum m(0, 2, 4, 5, 10, 11, 13, 15).$

- Minimization of POS. Consider the maxterms for which f = 0 and combine them into sum terms that are of the largest groups possible. Then form the product of the minimum-cost cover of the sum terms.
- Alternatively, find the minimum-cost SOP of the complement of *f*, and then apply DeMorgan's theorem to the expression to obtain the minimum-cost POS realization of *f*.

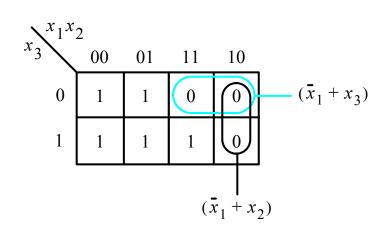


Figure 4.13. POS minimization of $f(x_1, x_2, x_3) = \prod M(4, 5, 6)$.

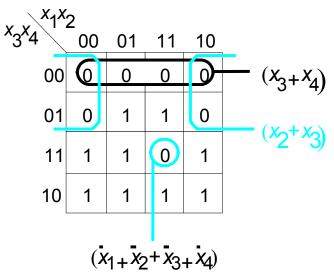


Figure 4.14. POS minimization of $f(x_1,...,x_4) = \prod M(0, 1, 4, 8, 9, 12, 15).$

Minimization of Incompletely Specified Functions

- A function that has *don't care* conditions is said to be incompletely specified. This happens, for example, if certain input conditions can never occur.
- Don't cares can be used to advantage in the design of logic circuits. Example: Find the simplest SOP and POS for the following function.

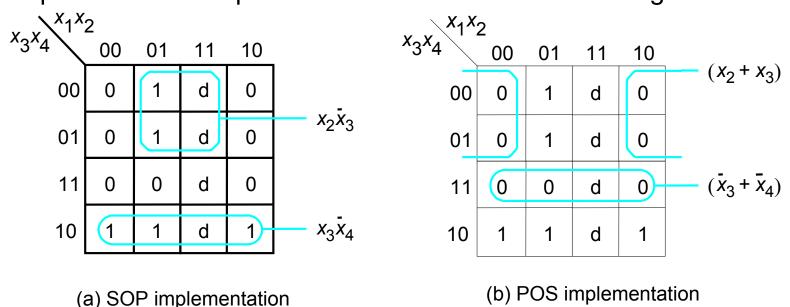


Figure 4.15. Two implementations of the function
$$f(x_1,...,x_4) = \sum m(2, 4, 5, 6, 10) + D(12, 13, 14, 15).$$
 Chapter 4-15

Tabular Method for Minimization

- The technique described here is called *Quine-McClusky methd*.
- We will use cube representation for the prime implicants.
- This method involves two major tasks:
 - 1) Generation of all prime implicants of the logic function
 - 2) Determination of a minimum-cost cover from all the prime implicants
- The steps are detailed below:
- 1. Generate all the prime implicants by successive pairwise comparison of the cubes
- 2. Derive a cover table which indicates the minterms of *f* covered by each prime implicant
- 3. Include the essential prime implicants (if any) in the final cover and reduce the table by removing both these prime implicants and the covered minterms
- 4. Use the concept of row and column dominance to reduce the cover table further. A dominated row is removed only if the cost of its prime implicant is greater than or equal to the cost of the dominating row's prime implicant.
- 5. Repeat steps 3 and 4 until the cover table is either empty or no further reduction is possible
- 6. If the reduced cover table is not empty, then use the branching approach to determine the remaining prime implicants that should be included in a minimum-cost cover

Tabular Method for Minimization

Example: Determine all the prime implicants of the function defined by $f(x_1,...,x_4) = \Sigma m(0, 4, 8, 10, 11, 12, 13, 15)$

• Next find a minimum-cost cover for *f*.

Final minimal cover of f is given by: C = Thus, the minimum-cost SOP for f is: f =

Tabular Method for Minimization

- The tabular method can also be used for minimization of functions with don't care conditions.
- Example: $f(x_1, \dots, x_4) = \Sigma m(0, 2, 5, 6, 7, 8, 9, 13) + D(1, 12, 15)$

Final minimal cover of f is given by: C = Thus, the minimum-cost SOP for f is: f =

Tabular Method for Minimization

• In the following example, there are no essential prime implicants and no dominant rows or colums. Moreover, all prime implicants have the same cost. In this case the concept of *branching* is used.

 $f(x_1,...,x_4) = \Sigma m(0, 3, 10, 15) + D(1, 2, 7, 8, 11, 14)$

Practical Considerations

- The Tabular method is relatively easy to understand but has some drawbacks if considered for CAD implementation.
- The main difficulty is that the number of cubes that must be considered in the process can be extremely large as it first tries to obtain *all* the prime implicants of the function.
- Heuristic techniques that produce good results in reasonable time are preferred specially for functions of large number of variables.
- The *Espresso* algorithm from UC Berkley is one such example.
- CAD tools provide logic synthesis software that can be used to target various types of chips, such as PLDs, gate arrays, standard cells, and custom chips.
- The process in logic design & implementation by such tools include:
 - > Technology-independent logic synthesis
 - Technology mapping